

GYRO STABILIZATION MOUNTS







MARINE

AIRBORNE

LAND



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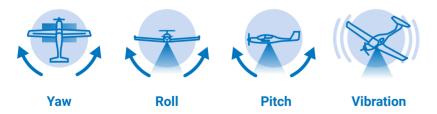
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Pitch, roll and yaw angles present a constant challenge for aerial photography, geospatial data acquisition and surveillance. The solution – Gyro Stabilization Mounts, which drastically reduce the movements of airborne sensor systems. Our three axes gimbals automatically compensate arbitrary vehicle movements and vibrations in all three axes. This technology ensures a high-resolution image quality and more flying time at lower costs. All SOMAG Mounts can be connected with the most popular Inertial Measurement Units (IMUs) and Flight Management Systems (FMS') to complete flight missions even more efficiently.

Movements stabilized by SOMAG Airborne Mounts:



Compatible with:

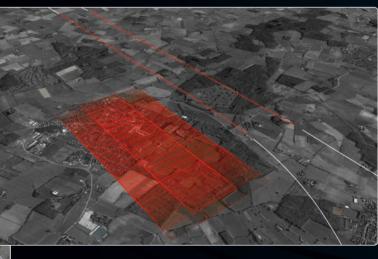
- Aerial Cameras
- Hybrid Mapping Systems
- Multispectral Cameras
- Hyperspectral Cameras
- · LiDAR Systems
- Radar Systems

AIRBORNE

DATA COMPARISONAIRBORNE CAMERA

© SOMAG GSM 4000





Without Stabilization

- Lack of adjacent overlap could cause missing data
- Large overlap to avoid missing data costs time and money, which results in an inefficient workflow
- The acquisition of blurred images causes more post-processing issues
- Ranging errors for LiDARs because of aircraft pitch movement

With Stabilization

- Turbulences are stabilized & risk of data gaps is highly reduced
- Overlap can be highly reduced, which saves time, money and enables an efficient workflow
- Smearing of images is highly reduced
- Pitch compensation increases ranging accuracy of LiDARs

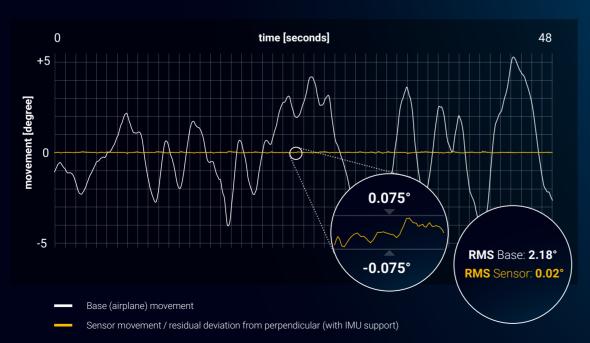


KEY FEATURES AIRBORNE MOUNTS

- High stabilization accuracy: Using a SOMAG Airborne Mount reduces the existing movements at the sensor usually by 50 times¹
- Highest compatibility on the market with existing airborne sensor systems
- Passive Vibration Isolation Rings for all Airborne Mounts
- User-friendly interface and easy handling
- Minimal weight and dimensions by maintaining maximum performance
- Usable with SOMAG Mount Control App

STABILIZATION ACCURACY SOMAG MOUNTS (ROLL AXIS)

The use of a SOMAG Airborne Mount reduced the existing movements in this mission data example² by ca. 110 times³ for the sensor system



- The factor may vary depending on the base excitation and IMU accuracy
- ² Vehicle angular motion <10°/s with typical data acquisition profile frequency spectrum
- ³ Ratio RMS base movement to RMS sensor movement





		GSM 4000	DSM 400	CSM 40
Angular Stabilization Ranges	Pitch at 0° Roll:	≤±8.8°	≤±10.5°	≤±15.0°
	Roll at 0° Pitch:	≤±7.0°	≤±10.5°	≤±15.0°
	Yaw (drift):	≤±25.0°	≤±25.0°	≤±25.0°
Usable Diameter		Ø410 mm	Ø270 mm	Ø130 mm
		Ø16.1 in	Ø10.6 in	Ø5.1 in
Payload ¹		10120 kg	535 kg	015 kg
		22264.6 lbs	1177.1 lbs	033.1 lbs
Mass		29 kg	14 kg	5.2 kg
		63.9 lbs	30.9 lbs	11.5 lbs
Dimensions	Length:	615 mm 24.2 in	460 mm 18.1 in	290 mm 11.4 in
(Regular Leveling Positions)	Width:	530 mm 20.9 in	430 mm 16.9 in	275 mm 10.8 in
	Average Height ² :	175 mm 6.9 in	165 mm 6.5 in	121 mm 4.7 in

Preliminary data, subject to change

SPECIFICATIONS

- ¹ Minimum payload is based on usage of Passive Vibration Isolation Ring
- ² Minimum/maximum height see technical specification on product pages





The GSM 4000 is the flagship of the airborne product line and was developed for large format sensors. SOMAG's largest three-axis gimbal features a hydraulic gimbal system, making the Mount very powerful. The GSM 4000 stabilizes payloads up to 120 kg with a self-weight of only 29 kilos. The control panel on the top of the Mount guarantees a user-friendly handling. Via the USB port, the gimbal can be connected to the SOMAG Mount Control App. In addition, the aux port interface is also available for this Mount now.

The Gyro Stabilization Platform offers a lift-up function for easy access to the camera lens or the bottom of the sensor.

The GSM 4000 is the successor to the world-renowned GSM 3000 and is 100 % downward compatible with current GSM 3000 installations. If you want to exchange your GSM 3000 for a new GSM 4000, SOMAG offers a trade-in at special conditions.

Field of Application





Application Examples



Vexcel UltraCams



Riegl LiDARs



Teledyne Optech LiDARs



IGI Mapping Systems

TECHNICAL SPECIFICATIONS

@ SOMAG GSM 4000

Angular Stabilization Ranges	Pitch at 0° Roll:	≤± 8.8°
	Roll at 0° Pitch:	≤± 7.0°
	Yaw (Drift):	≤± 25.0°
Residual Angular Rate ¹		≤± 0.2°/s rms
Residual Deviation ¹	without IMU support:	≤0.3° rms
	with IMU support ² :	≤0.02° rms
Payload ³		10120 kg 22264.6 lbs
Mass		29 kg 63.9 lbs
Dimensions	Length:	615 mm 24.2 in
(Regular Leveling Positions)	Width:	530 mm 20.9 in
	Height ⁴ :	175 mm 6.9 in
Usable Diameter		Ø410 mm Ø16.1 in
Operating Temperature		-15 °C +55 °C -5 °F +131 °F
Storage Temperature		-55 °C +85 °C -40 °F +185 °F
Communication Interfaces		RS 232 USB
Operational Voltage		28 VDC (2430 VDC)
Average Power Consumption at Operational Voltage		50 W
Peak Power Consumption at Operational Voltage		180 W
Applied Standards		RTCA DO-160-G, EUROCAE-14G, ISO 7137,

2006/42/EC Machinery

GSM 4000

Preliminary data, subject to change

- ¹ Vehicle angular motion <10°/s and with typical data acquisition profile frequency spectrum
- ² Deviation from perpendicular depends on accuracy of used IMU
- ³ Minimum payload is based on usage of Passive Vibration Isolation Ring
- ⁴ Minimum 149.5 mm (5.8 in) | Maximum 200.5 mm (7.9 in)





DSM 400 DYNAMIC STABILIZATION MOUNT

The DSM 400 is a cost efficient and mid-size modular stabilization device for multiple medium format cameras and sensors. The Mount features an electro-mechanical gimbal system and supports the reduction of the angular rate to provide optimal stabilization of the sensor system. The Mount features a simplified and redesigned control panel. The panel includes one FMS port and an USB port to connect with our SOMAG Mount Control App. The DSM is complemented by a Passive Vibration Isolation Ring to decouple high-frequency vibrations of the aircraft.

Field of **Application**



AIRBORNE

Application Examples



Phase One Aerial Systems



Riegl VUX Series



HySpex VNIR - 1800 Itres microCASI 1920



TECHNICAL SPECIFICATIONS

Angular Stabilization Ranges Pitch at 0° Roll:	≤± 10.5′
Roll at 0° Pitch:	≤± 10.5°
Yaw (Drift):	≤± 25.0°

	Yaw (Drift):	≤± 25.0°
Residual Angular Rate ¹		≤± 0.5°/s rms
Residual Deviation ¹	without IMU support	≤0.3° rms
	with IMU support ² :	≤0.08° rms
Payload ³		535 kg 1177.2 lbs
Mass		14 kg 30.9 lbs
Dimensions	Length:	460 mm 18.1 in
(Regular Leveling Positions)	Width:	430 mm 16.9 in
	Height ⁴ :	165 mm 6.5 in
Usable diameter		Ø270 mm Ø10.6 in
Operating Temperature		-15 °C +55 °C -5 °F +131 °F
Storage Temperature		-55 °C +85 °C -40 °F +185 °F
Communication Interfaces		RS 232 USB
Operational Voltage		28 VDC (2430 VDC)
Average Power Consumption at Operational Voltage		30 W
Peak Power Consumption at Operational Voltage		120 W
Applied Standards		RTCA DO-160-G, EUROCAE-14G, ISO 7137,
		2006/42/EC Machinery

Preliminary data, subject to change

- Vehicle angular motion <10°/s and with typical data acquisition profile frequency spectrum
- ² Deviation from perpendicular depends on accuracy of used IMU
- ³ Minimum payload is based on usage of Passive Vibration Isolation Ring
- ⁴ Minimum 131 mm (5.1 in) | Maximum 199 mm (7.8 in)





CSM 40 COMPACT STABILIZATION MOUNT

The CSM 40 features an electro-mechanical gimbal system and is extra small and cost efficient. The device is characterized by its minimum dimensions and low weight. The compact design and highly functional modularity enable a powerful mounting system, which is particularly suitable for ultralight aircraft and UAVs. The Mount is designed to stabilize single medium format cameras and sensors. Like all SOMAG Airborne Mounts, the CSM 40 offers an easy-to-use control panel and can optionally be ordered with a Passive Vibration Isolation Ring.

Field of Application



AIRBORNE

Application Examples



Phase One Cameras



Telops Hyperspectral Camera



Specim AisaKESTREL

CSM 40

TECHNICAL SPECIFICATIONS

Angular Stabilization Ranges	Pitch at 0° Roll:	≤± 15.0°
	Roll at 0° Pitch:	≤± 15.0°
	Yaw (Drift):	≤± 25.0°
Residual Angular Rate ¹		≤± 0.5°/s rms
Residual Deviation ¹	without IMU support:	≤0.3° rms
	with IMU support ² :	≤0.08° rms
Payload		015 kg 033.1 lbs
Mass		5.2 kg 11.5 lbs
Dimensions	Length:	290 mm 11.4 in
(Regular Leveling Positions)	Width:	275 mm 10.8 in
	Height ³ :	121mm 4.8 in
Usable Diameter		Ø130 mm Ø5.1 in
Operating Temperature		-15 °C +55 °C -5 °F+131 °F
Storage Temperature		-55 °C +85 °C -40 °F+185 °F
Communication Interfaces		RS 232 USB
Operational Voltage		28 VDC (2430 VDC)
Average Power Consumption at Operational Voltage		15 W
Peak Power Consumption at Operational Voltage		60 W
Applied Standards		RTCA DO-160-G, EUROCAE-14G, ISO 7137,
		2006/42/EC Machinery

Preliminary data, subject to change

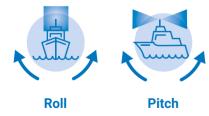
- $^{\,\,1}\,$ Vehicle angular motion <10°/s and with typical data acquisition profile frequency spectrum
- ² Deviation from perpendicular depends on accuracy of used IMU
- ³ Payload installation level: 110 mm | Minimum: 86 mm | Maximum 134 mm



HOW **SOMAG MARINE & LAND** MOUNTS WORK

SOMAG AG Jena develops and manufactures a range of Gyro Stabilization Mounts specifically for marine and land applications to perfectly stabilize sensors in extremely harsh environments. The stabilizers have been designed to be dust-, salt- and splash-water resistant. High-quality materials and a robust design guarantee an effective use of these mounting systems. The gyro stabilizers compensate roll and pitch motions of boats, ships, Unmanned Surface Vessels (USVs) and floating platforms caused by swell. They also stabilize roll and pitch motions of any kind of vehicle caused by uneven terrain, providing a stabilized field of view of the panoramic environment.

Movements stabilized by SOMAG Marine & Land Mounts:



Possible Marine Application:

- Maritime Patrol and Coastal Surveillance
- Search and Rescue Missions
- · Anti-Collision Systems on USVs
- Offshore Data Transmission
- Offshore Survey





Roll

Pitch

Possible Land Application:

- Border and Force Protection
- Mobile Mapping and Scanning
- Agriculture
- Mining Vehicles
- Chemical Detection

MARINE & LAND

DATA COMPARISONMARITIME SURVEILLANCE SYSTEM





- Pin-sharp images
- High quality video recording
- Perfectly stabilized Field of View
- Enhanced situational awareness
- Improved detection and tracking of moving objects even from a distance and in harsh environments

Without Stabilization

- Imaging system follows vessel motion caused by swell
- Unstable Field of View and decreased data quality
- Deterioration of detection, tracking and pointing capabilities of sensor systems

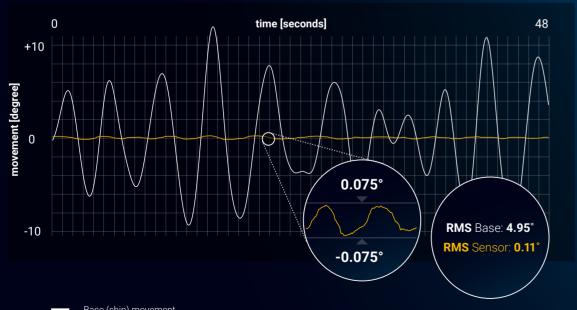


KEY FEATURES MARINE AND LAND **GYRO MOUNTS**

- Ruggedized design for use in harsh off-road and offshore environments
- High stabilization accuracy: Using a SOMAG Marine & Land Mount reduces the existing movements at the sensor by ca. 45 times1
- IP-67 compliant (dust-, salt- and splash-water resistant)
- innovative round shape enables compatibility with a wide range of payloads
- operation down to -30 °C possible
- Import of external IMU data or NMEA frames possible
- Usable with SOMAG Mount Control App

STABILIZATION ACCURACY SOMAG MOUNTS (ROLL AXIS)

The use of a SOMAG Marine Mount reduced the existing movements in this mission data example² by ca. 45 times³ for the sensor system



sor movement / residual deviation from perpendicular (without IMU support)



TECHNICAL SPECIFICATIONS

		OSM 5000	NSM 400	RSM 50
Angular Stabilization	Pitch at 0° Roll:	≤± 12.2° 14.1° (optional)	≤±20.0°	≤±20.0°
Ranges	Roll at 0° Pitch:	≤± 17.4° 14.1° (optional)	≤±20.0°	≤±20.0°
	Yaw (drift):	no drift correction	no drift correction	no drift correction
Payload ¹		300 kg 250 kg 200 kg 660 lbs 550 lbs 440 lbs	100 kg 70 kg 55 kg 220.5 lbs 154.3 lbs 121.3 lbs	40 kg 25 kg 12.5 kg 88.2 lbs 55.1 lbs 27.6 lbs
Mass		55 kg 120 lbs	33 kg 72.5 lbs	11.5 kg 24.3 lbs
Dimensions / Height		290 mm 11.4 in	290 mm 11.4 in	197.5 mm 77.8 in
Dimensions / Diameter		Ø665 mm Ø26.1 in	Ø486 mm Ø19.1 in	Ø306 mm Ø12 in

Preliminary data, subject to change

The factor may vary depending on the base excitation and IMU accuracy

² Real ship motion data recorded from LNG tanker at sea state 7

¹ Possible payload weight depends on lateral acceleration and CoG of payload - see technical specification on product pages





The OSM 5000 combines power with versatility. A combination of high-torque engines and a hydraulic gimbal system enables the Mount to lift an unprecedented payload up to 300 kilograms. The weatherproof design makes this device extremely ruggedized for land and marine usage. Even harsh conditions set no limits to its functionality and precise performance. The OSM 5000 offers and usable mounting space of Ø665 mm with sufficient space for a wide range of large sensor systems and antennas. The Mount is equipped with an Ethernet port to integrate it into an existing network.

Field of Application





MARINE

LAND

Application Examples







Radar System

TECHNICAL SPECIFICATIONS

Angular Stabilization Ranges	Pitch at 0° Roll:	≤± 12.2° 14.1° (optional)
	Roll at 0° Pitch:	≤± 17.4° 14.1° (optional)
	Yaw (Drift):	no drift correction
Residual Deviation		≤0.3° rms
Payload ²		300 kg 250 kg 200 kg
		660 lbs 550 lbs 440 lbs
Continuous Torque		275 Nm
Dynamic Peak Torque ³		550 Nm
Mass		55 kg 120 lbs
Dimensions	Height:	290 mm 11.4 in
	Diameter:	Ø665 mm Ø26.1 in
IP Class		IP 67
Operating Temperature		-32 °C +55 °C -25.6 °F +131 °F
Storage Temperature		-55 °C +85 °C -67 °F +185 °F
Communication Interfaces		Ethernet RS422 RS232
Operational Voltage		48 VDC (4452 VDC)
Average Power Consumption ⁴ at Operational Voltage		100 W
Peak Power Consumption ⁴ at Operational Voltage		950 W
Applied Standards		IACS E10, DNV GL, 2006/42/EC Machinery

OSM 5000

Preliminary data, subject to change

- ¹ Vehicle motion ≤± 12° / 12°/s / 10°/s² small periodical lateral accelerations (≤ 0.5 g) acceptable, constant lateral accelerations for more than 1 minute reduce the performance of the Mount (can be compensated by external GPS input)
- ² Possible payload weight depends on lateral acceleration and CoG of payload / shown data is based on 0.5 g lateral acceleration and a CoG payload offset to the Mount surface of: 370 mm (14.6 in) | 450 mm (17.7 in) | 550 mm (21.7 in)
- ³ Maximum duration 90 s at 55 °C surrounding temperature | longer if temperature inside the unit is < 55 °C
- ⁴ Horizontal payload CoG offsets are not considered; without wind force and other possible external forces





The NSM 400 was designed for the stabilization of sensor systems on medium (starting from 1.0 kt onwards) to large maritime vessels and land vehicles. Like all SOMAG Marine and Land Mounts, the NSM 400 is IP 67 compliant and made to perform in very rough weather conditions and ensures high image quality capturing while maneuvering through high waves or driving over bumpy terrain. To achieve this performance, the NSM 400 features a peak torque of 250 Nm. The Mount offers both, a large stabilization range to compensate movements up to ≤±20° in roll and pitch and an unmatched stabilization accuracy without external IMU data. The Mount is equipped with an Ethernet port to integrate it into an existing network.

Field of Application





MARINE

LAND

Application Examples







Pan/Tilt Camera

NSM 400

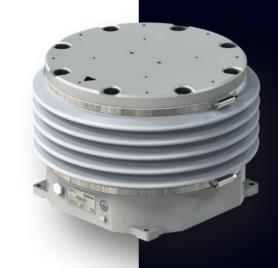
TECHNICAL SPECIFICATIONS

Angular Stabilization Ranges	Pitch at 0° Roll:	≤± 20.0°
	Roll at 0° Pitch:	≤± 20.0°
	Yaw (Drift):	no drift correction
Residual Deviation		≤0.4° rms
Payload ²		100 kg 70 kg 55 kg
		220.5 lbs 154.3 lbs 121.3 lbs
Continuous Torque		125 Nm
Dynamic Peak Torque ³		250 Nm
Mass		33 kg 72.5 lbs
Dimensions	Height:	290 mm 11.4 in
	Diameter:	Ø486 mm Ø19.1 in
IP Class		IP 67
Operating Temperature		-30 °C +55 °C -22 °F +131 °F
Storage Temperature		-55 °C +85 °C -67 °F +185 °F
Communication Interfaces		Ethernet RS422 RS232
Operational Voltage		28 VDC (2430 VDC)
Average Power Consumption ⁴ at Operational Voltage		90 W
Peak Power Consumption ⁴ at Operational Voltage		450 W
Applied Standards		IACS E10, DNV GL, 2006/42/EC Machinery

Preliminary data, subject to change

- ¹ Vehicle motion ≤± 18° / 15°/s / 40°/s² small periodical lateral accelerations (≤ 0.5 g) acceptable, constant lateral accelerations for more than 1 minute reduce the performance of the Mount (can be compensated by external GPS input)
- Possible payload weight depends on lateral acceleration and CoG of payload | shown data is based on 0.9 g lateral acceleration and a CoG payload offset to the Mount surface of: 250 mm (9.8 in) | 400 mm (15.7 in) | 500 mm (19.7 in)
- 3 Maximum duration 90 s at 55 °C surrounding temperature | longer if temperature inside the unit is < 55 °C
- ⁴ Horizontal payload CoG offsets are not considered; without wind force and other possible external forces





RSM 50

RSM 50RUGGEDIZED STABILIZATION MOUNT

The RSM 50 is the smallest and most cost-effective of SOMAG's marine and land stabilizers. The ruggedized gimbal compensates roll and pitch motions and is specifically designed to stabilize small and light weight sensor systems in off-road and offshore environments to capture high quality data. The Mount is dust-, salt- and splash-water resistant. The design of the base plate allows the adaptation of a wide range of cameras and scanners, making the device very versatile for various applications and even unmanned missions.

Field of Application





LAND

MARINE

Application Examples





Antenna System

LiDAR System

TECHNICAL SPECIFICATIONS

Angular Stabilization Ranges	Pitch at 0° Roll:	≤± 20.0°
	Roll at 0° Pitch:	≤± 20.0°
	Yaw (Drift):	no drift correction
Residual Deviation ¹		≤0.3° rms
Payload ²		40 kg 25 kg 12.5 kg
		88.2 lbs 55.1 lbs 27.6 lbs
Continuous Torque		25 Nm
Dynamic Peak Torque ³		50 Nm
Mass		11.5 kg 24.3 lbs
Dimensions	Height:	197.5 mm 7.8 in
	Diameter:	Ø306 mm Ø12 in
IP Class		IP 67
Operating Temperature		-32 °C +55 °C -25.6 °F +131 °F
Storage Temperature		-55 °C +85 °C -67 °F +185 °F
Communication Interfaces		Ethernet RS422 RS232
Operational Voltage		24 VDC (2430 VDC)
Average Power Consumption ⁴ at Operational Voltage		50 W
Peak Power Consumption ⁴ at Operational Voltage		250 W
Applied Standards		IACS E10, DNV GL, 2006/42/EC Machinery

Preliminary data, subject to change

- Vehicle angular motion ≤± 18° / 25°/s / 40°/s² small periodical lateral accelerations (≤ 0.5 g) acceptable, constant lateral accelerations for more than 1 minute resulting from vehicle's turning maneuvers are compensated by internal or external GPS input. No GPS input could reduce the performance of the Mount during turning maneuvers.
- Possible payload weight depends on lateral acceleration and CoG of payload | shown data is based on 1.0 g lateral acceleration and a CoG payload offset to the Mount surface of: 125 mm (4.9 in) | 200 mm (7.9 in) | 400 mm (15.7 in)
- ³ Maximum duration 90 s at 55 °C surrounding temperature | longer if temperature inside the unit is < 55 °C
- ⁴ Horizontal payload CoG offsets are not considered; without wind force and other possible external forces



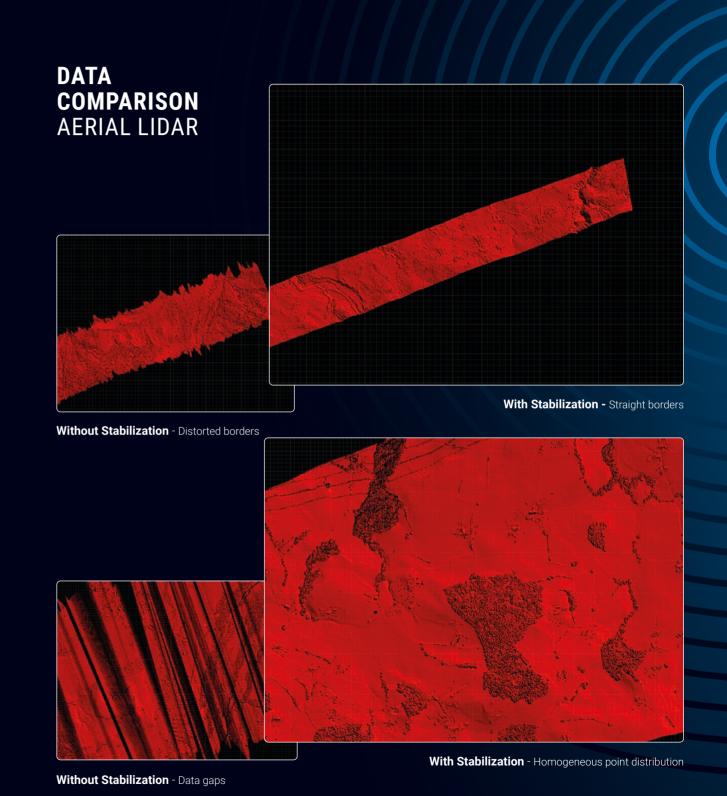
TECHNICAL BENEFITS OF AIRBORNE GYRO MOUNTS FOR **LIDAR SYSTEMS**

- · Compensation of random vehicle motions which ensures an even point density across the entire data set
- · Very homogeneous point distribution for LiDAR systems even at very high scan rates (e. g. 300 kHz)
- Regularly sampled and aligned data collection
- Improved collection efficiency (coverage)
- Predictable LiDAR point distribution (pitch variability in x-axis)
- · Automatic drift setting and initializing
- Decoupling of high frequency vibrations (>15 Hz) because of Passive Vibration Isolation Ring
- No pixel mixing under strong vibrations for hyperspectral scanners
- · Output of gimbal data at high data rates
- · Angular motion compensation
- · Remotely controlled operation via FMS
- · Adaptable to sensor weight from 0 to 120 kg
- · SOMAG Mount Control App for easy initial setup and diagnosis

STABILIZATION IS OF KEY IMPORTANCE

The most important criteria in a LiDAR capture project is point density [...]. The big "advantage" of having the gimbal is that: Smaller margins are required to fulfill point density requirements, which reduces flying time and project costs & the risk for data gaps is decreased substantially, which reduces cost for re-flying.

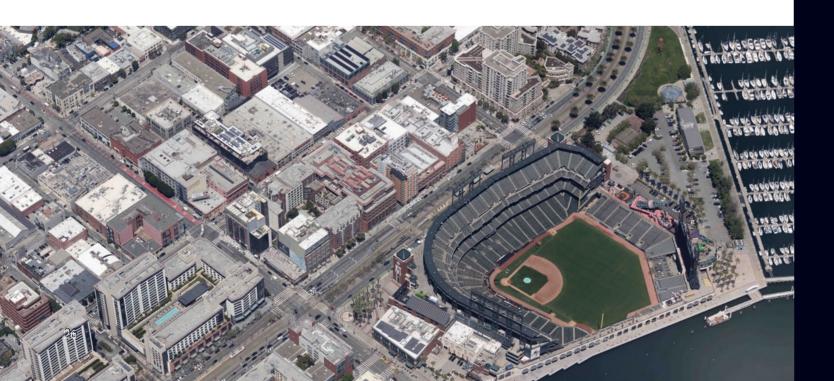
Dragan Vogel, Swiss Flight Services SA





TECHNICAL BENEFITS OF AIRBORNE GYRO MOUNTS FOR **CAMERA SYSTEMS**

- · Precise camera stabilization guarantees a high quality for orthogonal and oblique images
- · Overlap can be highly reduced for an economical data acquisition process
- Risk of data gaps is highly minimized
- Output of gimbal data at high data rates
- Angular motion compensation prevents image smearing
- Remotely controlled operation via FMS
- Adaptable to sensor weight from 0 to 120 kg
- Automatic and independent operation
- SOMAG Mount Control App for easy initial setup and diagnosis
- · Automatic drift setting and initializing
- Compensates not only aircraft movements like roll, pitch and yaw, but also vibrations
- Decoupling of high frequency vibrations (> 15Hz) because of Passive Vibration Isolation Ring



DATA COMPARISONAERIAL IMAGERY



Without Stabilization

With Stabilization



Without Stabilization

With Stabilization



SOMAG MOUNT CONTROL APP

For all Gyro Mounts SOMAG AG Jena provide its own developed SOMAG Mount Control App with numerous benefits:

- Quick Mount status overview
- · Manual control of the Mount
- Setting of optional Software Features
- · Real-time Mount feedback
- Self-test for quick status analysis
- · Simple firmware update
- · Access to all documents e.g. user manuals
- · Input and reporting functions directly accessible



Home view example in SOMAG Mount Control App



Software Feature configurations in Settings 1 view

OPTIONAL SOFTWARE FEATURES

SOMAG offers optional Software Features which allow you to customize your Mount individually to your mission requirements.

The following features can be ordered optionally:

- Leveling Offset: adjustment of the Mount virtual horizon
- End Stop Limits incl. Block Axis: adjustment of the Mount movement range
- Collision Avoidance: adjustment of Mount movement range and working height, in case of narrow installation condition
- Status/Analysis: logging and analyzing functions in SOMAG Mount Control App
- IMU Installation Position on Vehicle Frame: adjustment of horizontal IMU position
- Installation Direction: adjustment of Mount horizontal installation direction
- AUX port: enables communication to 3rd party interface



SENSOR ADAPTERS

Every project is different and so are the system requirements. We support you in the mechanical integration of your cameras, scanners and other payloads with our Gyro Stabilization Mounts. Upon request, our highly experienced engineers will design an adapter frame tailored to your individual needs that will 100 % meet the application conditions. The design of the sensor mounting system can vary between adapter frames for single medium format cameras and larger pods for the integration of multiple sensors. Together we will find the right solution for your requirements. Please contact us for more information and an individual consultation.



Adapter for multiple cameras mounted in oblique view



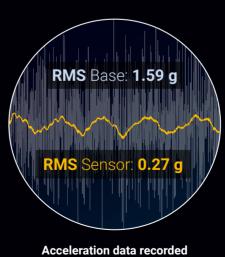
Airborne mapping system adapter



VIBRATION ISOLATION SYSTEMS

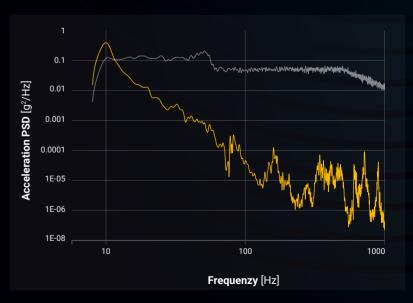
High-frequency vibrations of the aircraft floor can lead to severe damage to the sensitive sensor systems. By using a SOMAG Passive Vibration Isolation Ring (PaVIR), vibrations are drastically reduced which increases the data quality especially for scanners, LiDAR's and cameras. For the GSM 4000 and DSM 400, the PaVIR is part of the standard scope of delivery and adjusted accordingly to the weight of the payload. For the CSM, the ring can be ordered optionally. The rings are also available individually.

Using a SOMAG AG Jena **Passive Vibration Isolation Ring** reduces existing **vibrations** in an aircraft or other vehicles around **6 times** in all three axes.



Acceleration data recorded during a flight mission

Base (airplane) movement



Power Spectral Density analysis of the recorded data

Base (airplane) movement



SOMAG CUSTOMIZATION SERVICES

It is highly important for us to process orders on a customer-specific basis. Depending on the project, SOMAG will assist your company from concept through development to delivery of the whole system. The great flexibility of our company ensures that special customer wishes and changes are guaranteed. Our solutions are always durable, easy to handle and contain innovative technologies. SOMAG offers different customization services including Custom-Made Mounts and OEM Branding Services.





CUSTOM MADE MOUNTS

Our standard product portfolio does not reflect what you are looking for? Do you need a Mount that meets specific requirements? Then we are exactly the right partner for you! The design and manufacturing of Gyro Stabilization Mounts is our core business and there-

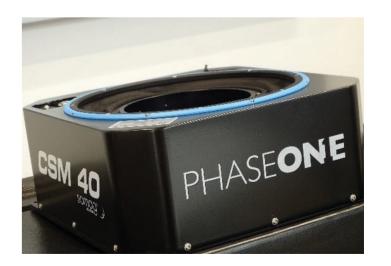


fore we can draw on many years of expertise when it comes to providing customized solutions. In the past years we have designed numerous Mounts in various configurations for our customers who approached us with special requests. A current example is the GSM 4000 Open Skies, which we manufactured on behalf of the German Federal Armed Forces. This Mount meets the special requirements of the aviation industry. We at SOMAG see each custom-made Mount as an engineering challenge that we gladly accept, as it contributes to our professional growth. Please get in touch with our experts about your project.

OEM BRANDING

SOMAG AG Jena has been working as an Original Equipment Manufacturer for numerous well-known camera, scanner and FMS manufacturers for several years. As an OEM partner, we offer our partner companies an individual product design. In this service we attach great importance to your company, your wishes and of course your end customers. When designing individual Gyro Stabiliziation Mounts, SOMAG follows your corporate design. Color design, logo and company name play a central role. These

features make your brand unmistakable and directly trigger an association with your company among your customers, which has an immediate impact on their purchase decision. Benefit from the SOMAG OEM Branding Service and increase your brand awareness with unique Gyro Mounts matching your visual system.





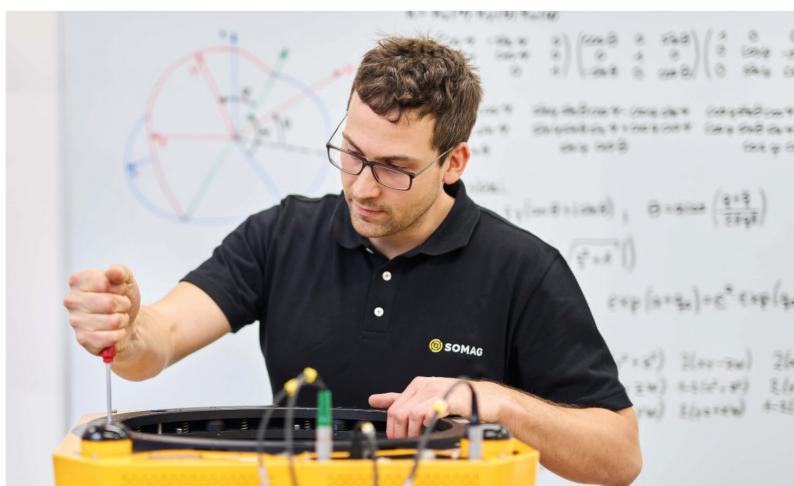
ABOUT **SOMAG AG JENA**

SOMAG AG Jena is a worldwide operating specialist for high-precision gimbal systems. The company, consisting of hand-picked experts in the fields of electronics, mechanics and software, focuses since 2004 on the development of Gyro Stabilization Mounts for data acquisition and surveil-lance applications. SOMAG is an ISO 9001 certified company and maintains a strict quality control system. All products are assembled and tested with highest precision at the headquarters in Jena, Germany and at independent test facilities.

The gimbal specialist works as an OEM partner of well-known camera and lidar manufacturers but has always maintained its status as an independent supplier in the market. SOMAG clients include commercial, governmental and defense organizations as well as research institutions.

The uniqueness of their customer projects and the multitude of different applications drives the SOMAG team to provide customized solutions and to improve performance with each newly developed device. This is why SOMAG Mounts set the pace for gyro stabilization devices worldwide.







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