

design and suitable for deployment on USVs and small buoys for sensor stabilization up to ≤± 20.0° in the roll and pitch axis.

TECHNICAL SPECIFICATIONS

Angular Stabilization Ranges	Pitch at 0° Roll:	≤± 20.0°
	Roll at 0° Pitch:	≤± 20.0°
	Yaw (Drift):	no drift correction
Residual Deviation ¹		≤0.3° rms
Payload ²		40 kg 25 kg 12.5 kg
		88 lbs 55 lbs 28 lbs
Continuous Torque		25 Nm
Dynamic Peak Torque ³		50 Nm
Mass		11.5 kg 24.3 lbs
Dimensions		197.5 mm 7.8 in
		Ø306 mm Ø12 in
IP Class		IP 67
Operating Temperature		-32 °C +55 °C -22 °F +131 °F
Storage Temperature		-55 °C +85 °C -67 °F +185 °F
Communication Interfaces		Ethernet RS422 RS232 (optional)
Operational Voltage		24 VDC (2430 VDC)
Average Power Consumption ⁴ at Operational Voltage		50 W
Peak Power Consumption ⁴ at Operational Voltage		250 W
		IACS E10, DNV GL, 2006/42/EC Machinery

Preliminary data, subject to change.

The technical specifications in the metric system represent the binding reference values. The imperial units are rounded approximations and are provided for reference only.

- Vehicle motion ≤± 18° / 25°/s / 40°/s² small periodical lateral accelerations (≤ 0.5 g) acceptable; constant lateral accelerations for more than 1 minute resulting from vehicle's turning maneuvers are compensated by internal or external GPS input. No GPS input could reduce the performance of the Mount during turning maneuvers.
- ² Possible payload weight depends on lateral acceleration and CoG of payload / shown data is based on 0.9 g lateral acceleration and a CoG payload offset to the Mount surface of: 250 mm (9.8 in) | 400 mm (15.7 in) | 500 mm (19.7 in)
- ³ Maximum duration 90 s at 55 °C surrounding temperature | longer if temperature inside the unit is < 55 °C
- ⁴ Horizontal payload CoG offsets are not considered; without wind force and other possible external forces





COMPACT AND LIGHTWEIGHT DESIGN

suitable for deployment on USVs and small buoys



IP 67

for high performance stabilization in rough maritime environments



INSTALLATION FLEXIBILITY

upside-down hanging application possibility



ETHERNET INTERFACE

for integration in ship's infrastructure

Field of Application



MARINE

Application Examples



Antenna System



LiDAR System



SCAN ME.

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